



```
marty.hello()
```

```
marty.celebrate()
```

```
marty.walk(1)
```

```
marty.sidestep('left')
```

```
marty.walk(2,'auto',0,-40,1500)
```

```
marty.sidestep('right')
```

```
marty.walk(5,'auto',100,0,1500)
```

```
marty.walk(5,'auto',-100,0,1500)
```